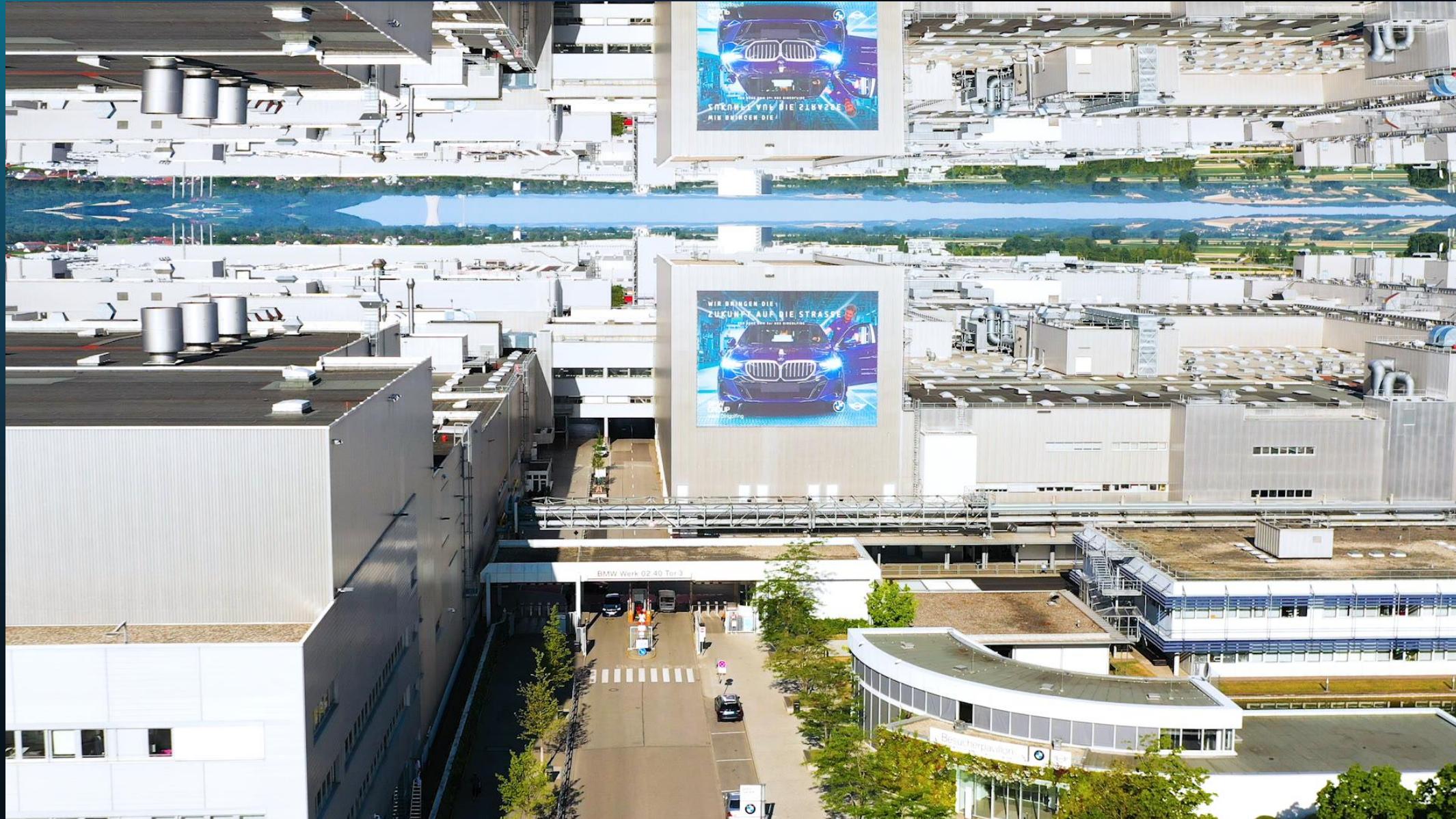




ROS IN MANUFACTURING

FROM INTEROPERABILITY TO PHYSICAL AI

/ POTENTIAL FOR SMART AUTOMATION



/ POTENTIAL FOR SMART AUTOMATION



/ AI-BASED IN-LINE QUALITY INSPECTION



Collision Avoidance

Web-based UI

Cycle Time Optimization

Kinesthetic Teaching

Enabling anyone to teach a robot to inspect in-line.

/ LESSONS LEARNED

System Building

Deployment

Operation

/ LESSONS LEARNED

System Building



Enabling maintenance personnel

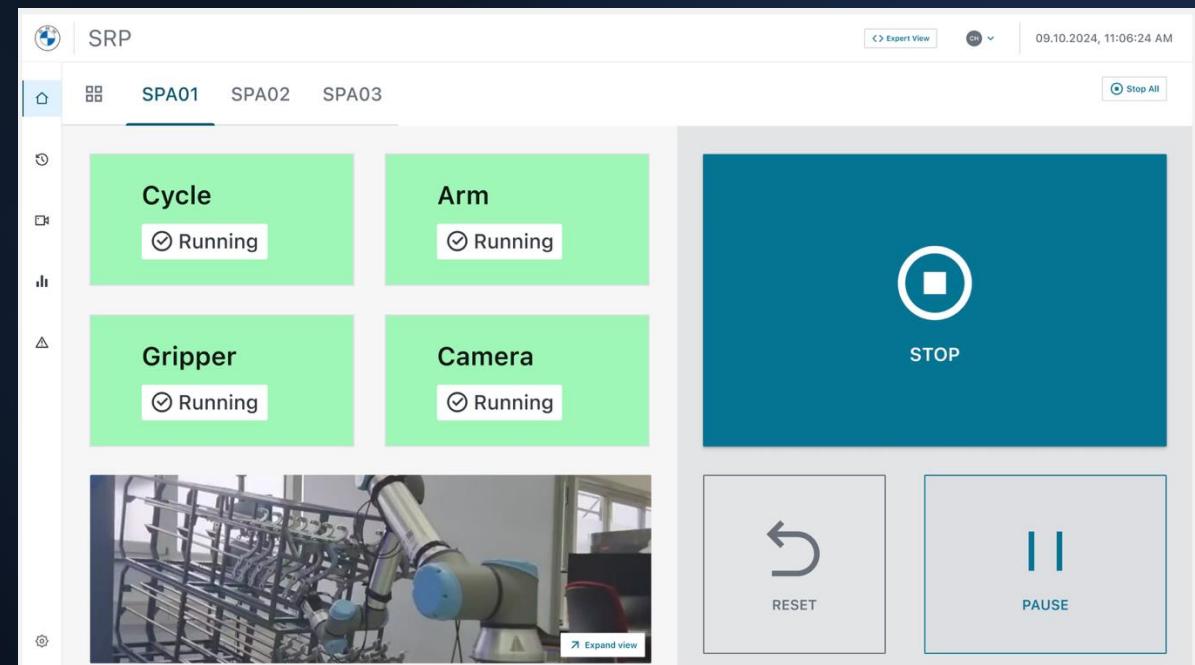


Allow for easy interaction

Deployment



Operation



/ MACHINE LOADING



2D Pose Estimation

BTs with Basic Recoveries

Advanced Safety

Showing that our robots can operate in production critical use cases.

/ LESSONS LEARNED

System Integration

Deployment

Operation

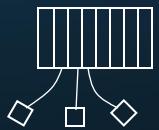
/ LESSONS LEARNED



System Integration



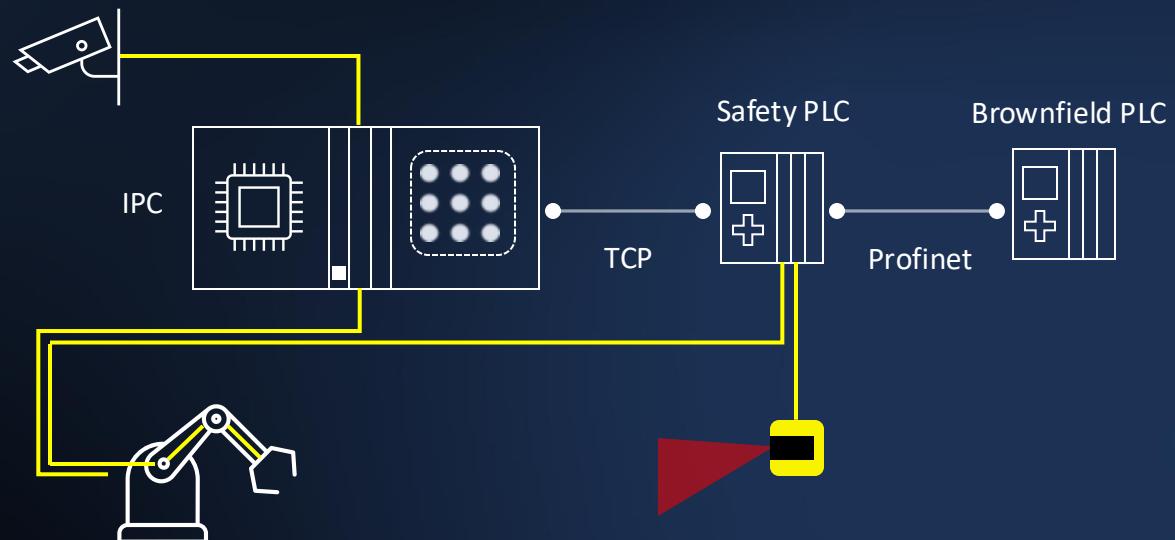
Network configurations



Abstracting I/Os

Deployment

Operation



/ SCALABLE MACHINE LOADING ROBOT



/ LESSONS LEARNED

System Integration

Deployment

Operation

/ LESSONS LEARNED

System Integration

Device Management

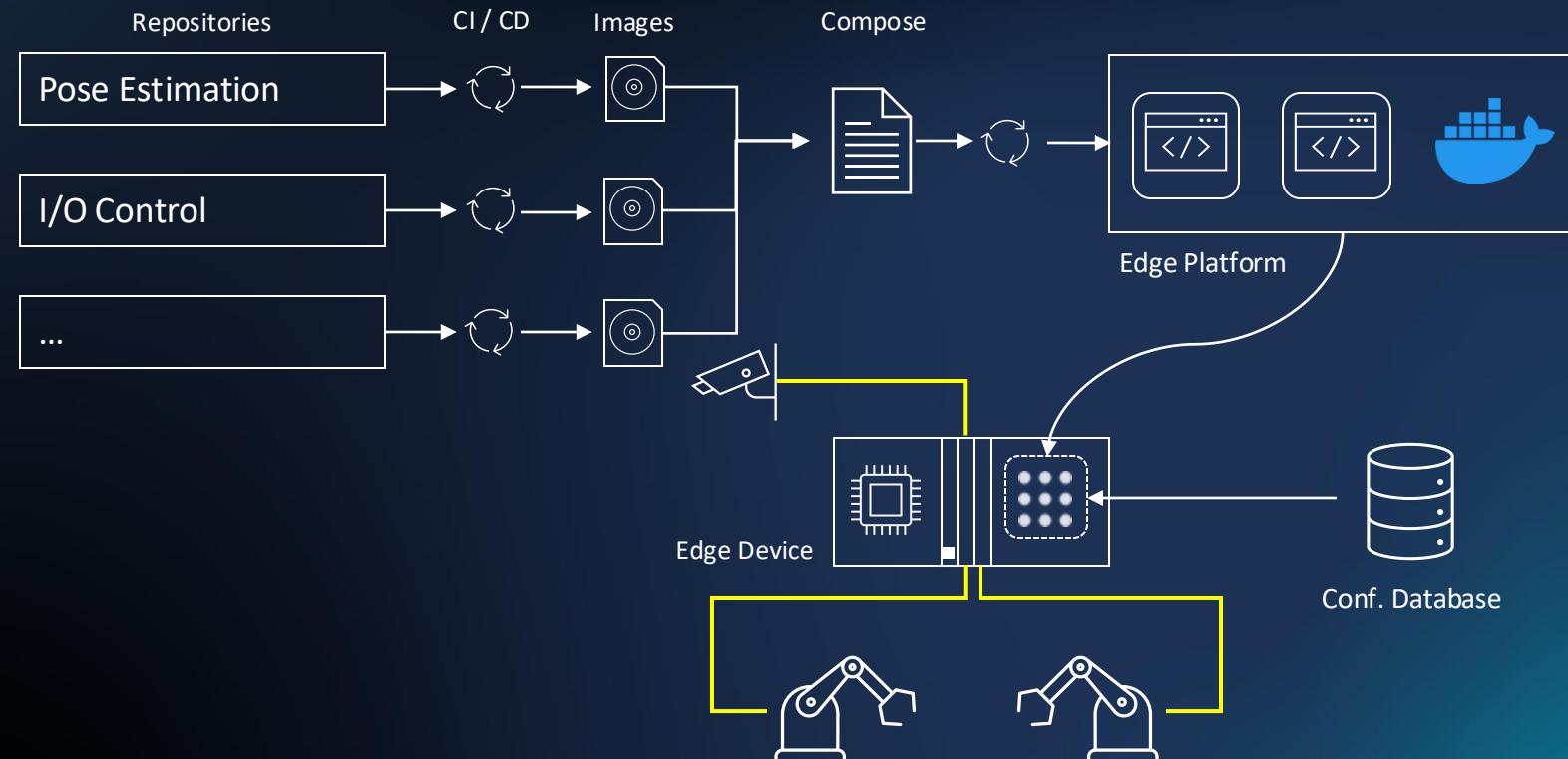
Packaging

Configuration Management



Deployment

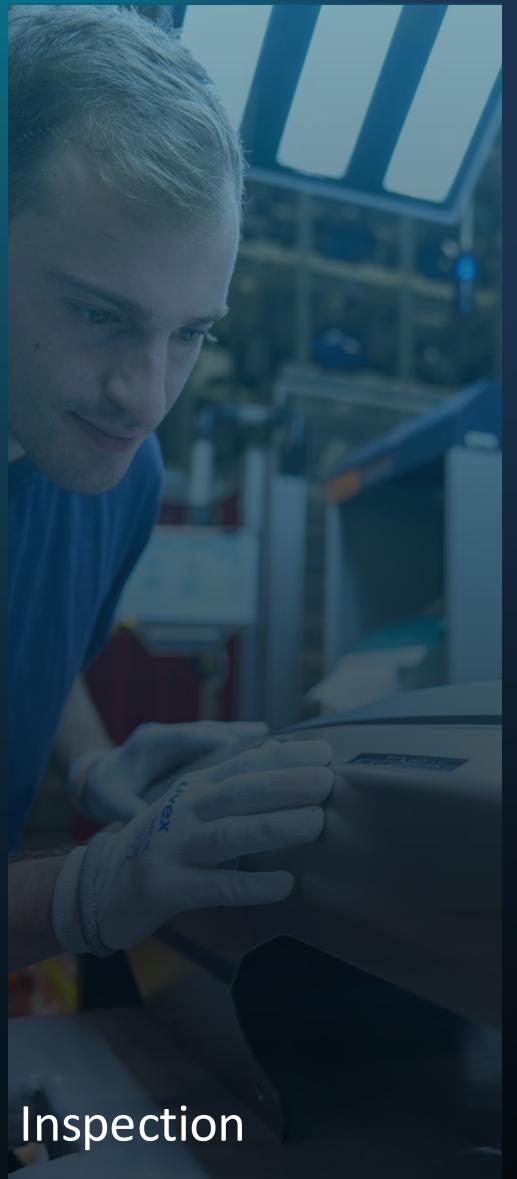
Operation



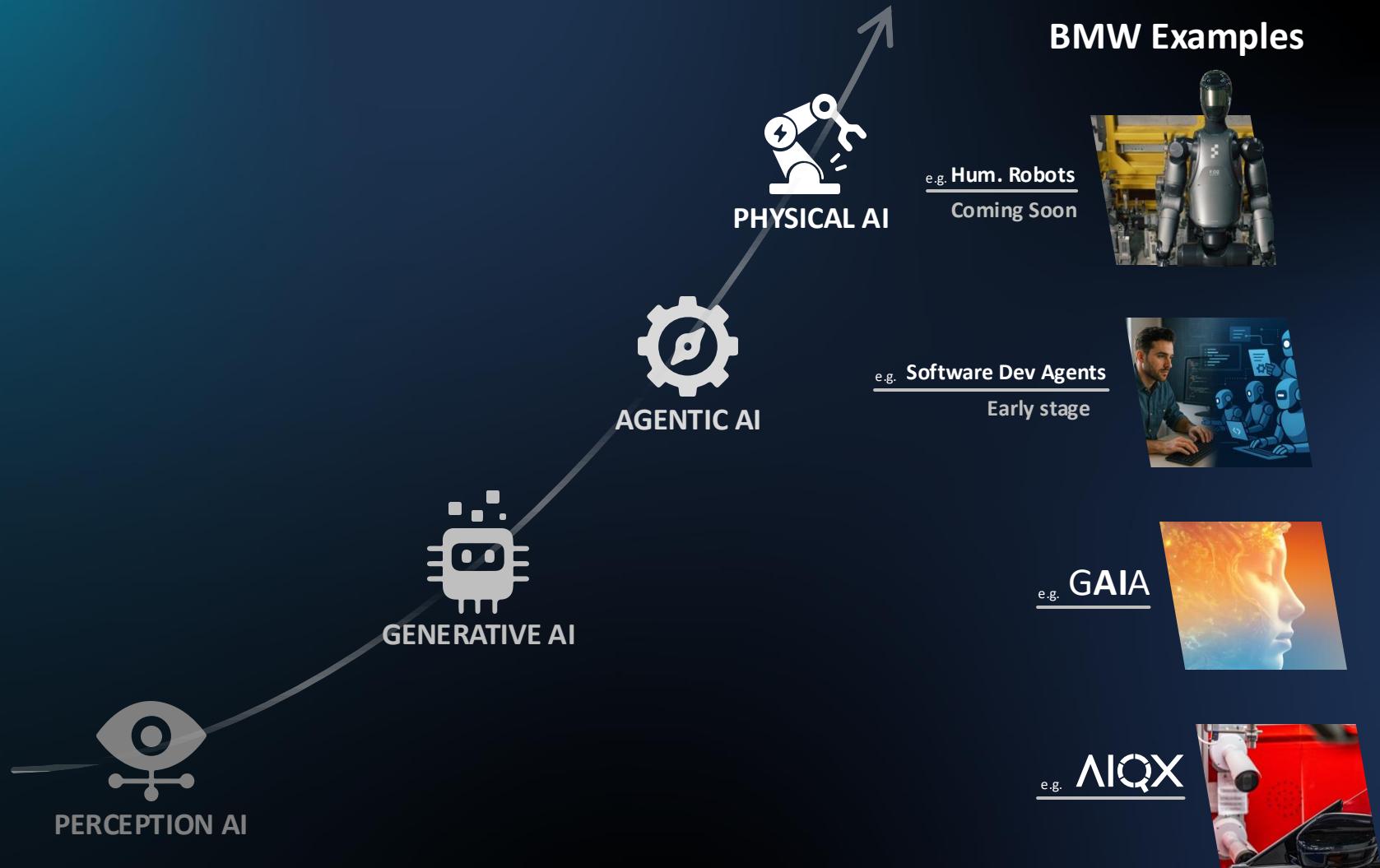
/ POTENTIAL FOR SMART AUTOMATION



/ POTENTIAL FOR SMART AUTOMATION



/ THE RACE TOWARDS PHYSICAL AI



/ NEXT LEAPS OF AI IN AUTOMATION



Perception



Mixed
Architectures

Specialized End-to-
End Policies

Orchestrator



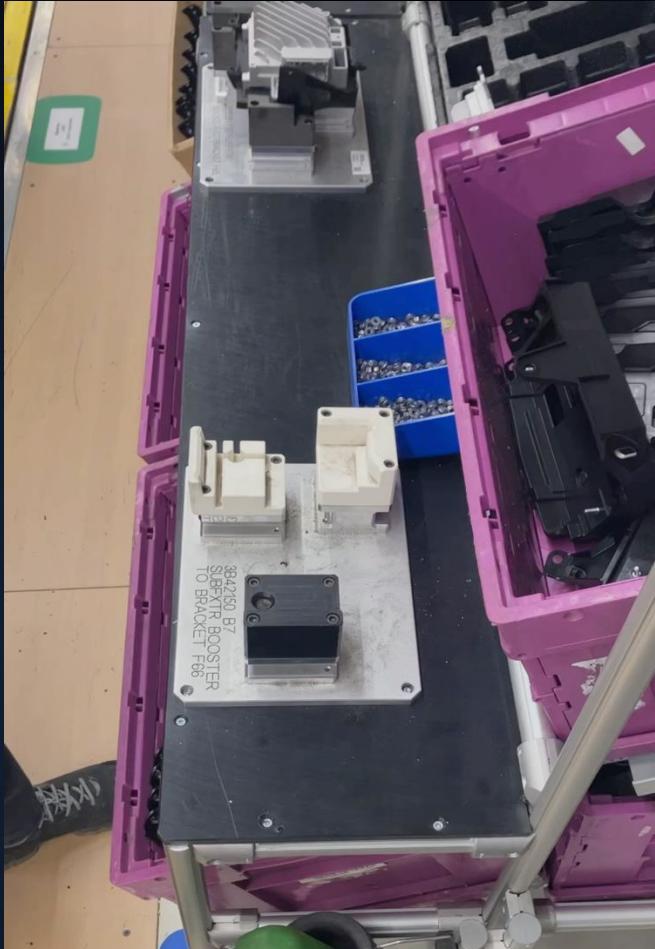
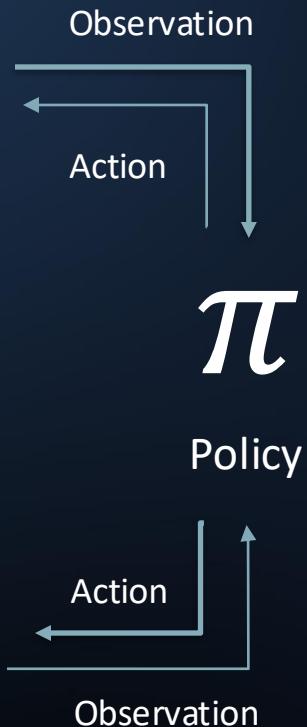
/ FROM HOUSEHOLD TO INDUSTRIAL TASKS



Source: Physical Intelligence



Source: Physical Intelligence



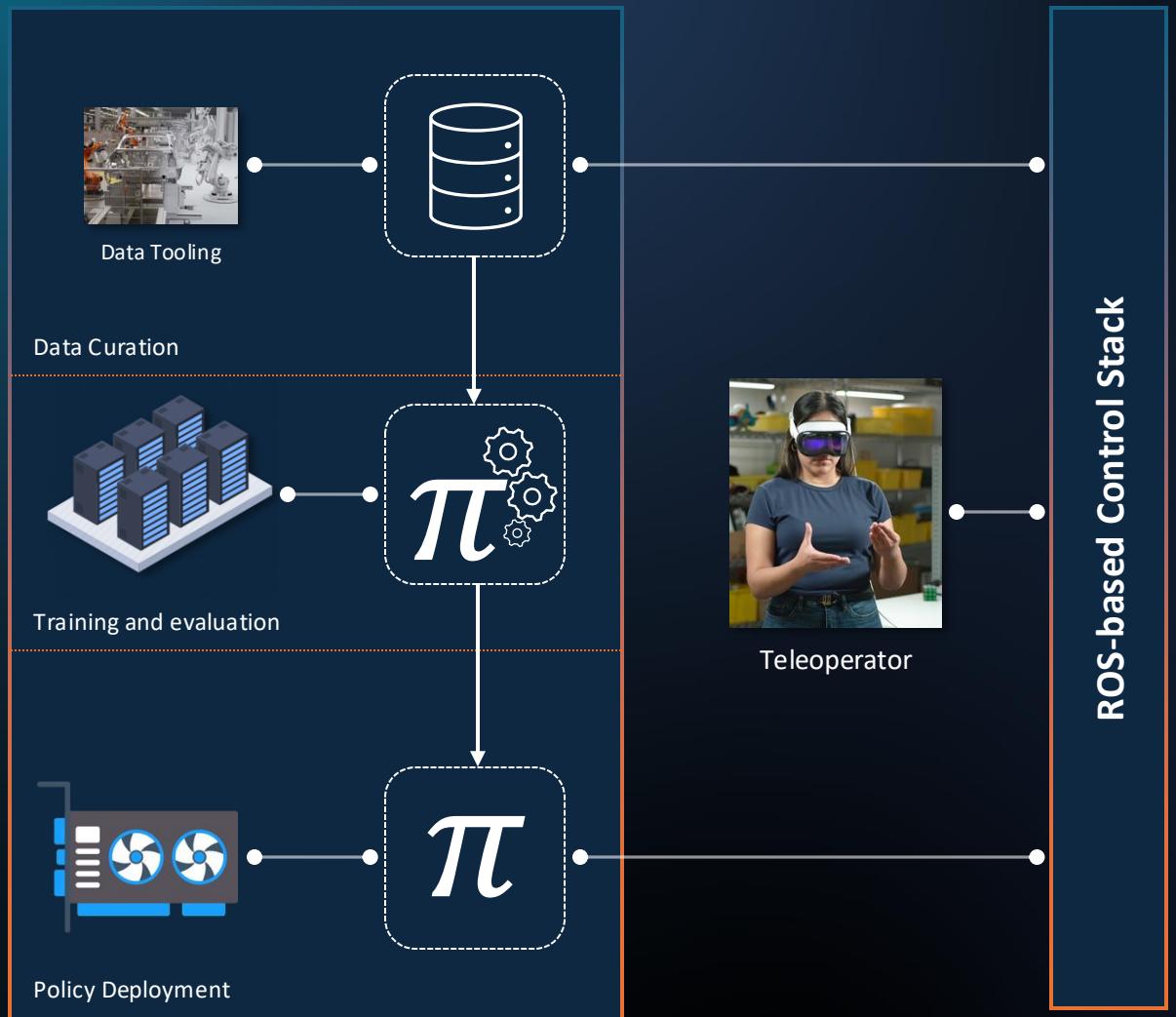
/ IMITATION LEARNING BY TELEOPERATION



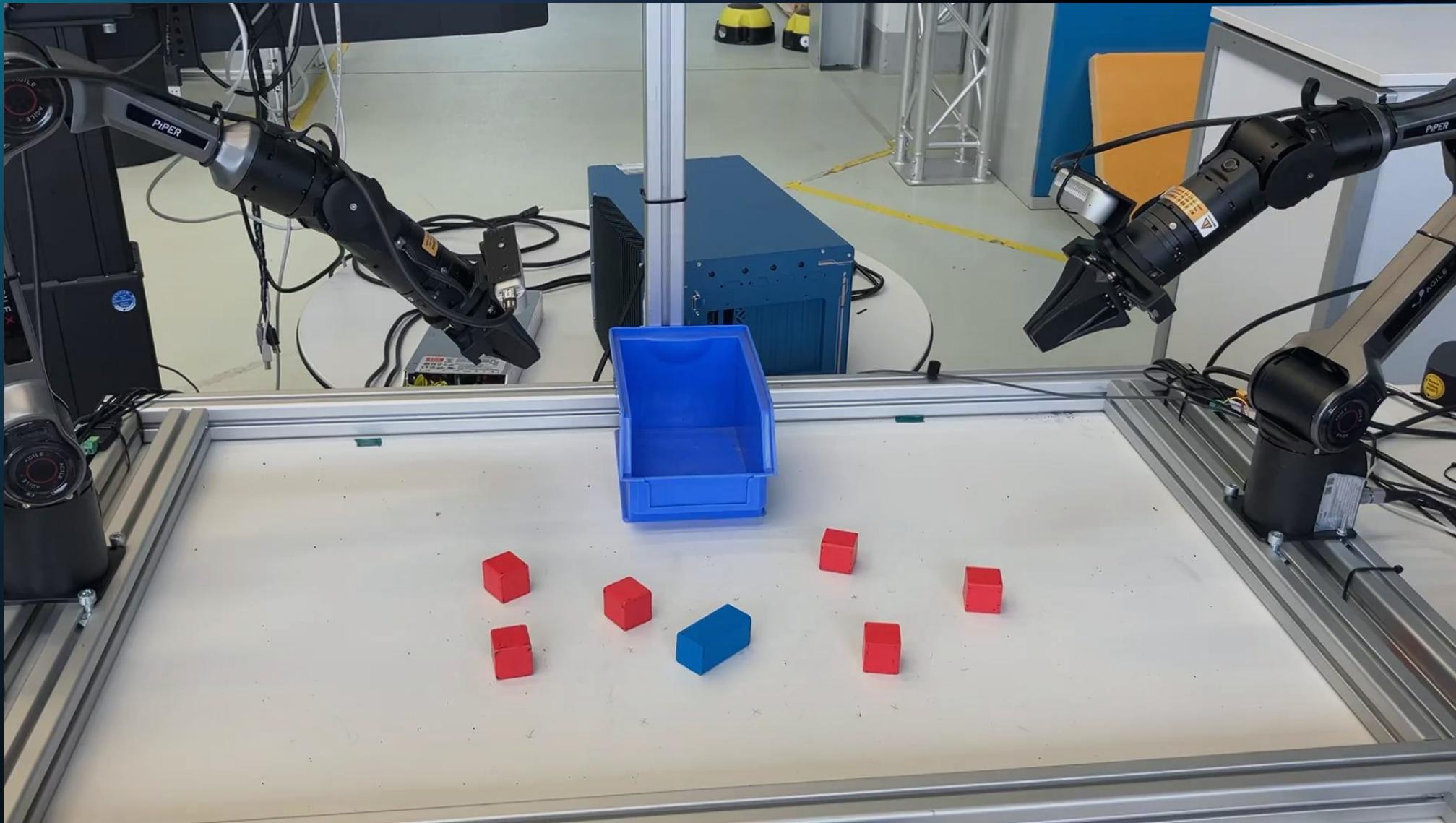
~1 Week per Cycle

/ INFRASTRUCTURE AND ACCESSIBILITY ARE KEY

Cloud



/ GRADUALLY INCREASING TASK COMPLEXITY



/ LESSONS LEARNED



Start small



Skilled
teleoperators



Evaluation is hard



/ FROM RESEARCH TO INDUSTRY ENABLING RESEARCH



/ BMW NEXT GEN ROBOTICS & COLLABORATORS

